

Last time: M^m manifold ..

Lemma: $X, Y \in \mathfrak{X}(M)$, then there exist another vector field $[X, Y] \in \mathfrak{X}(M)$,

$$\text{defined by } [X, Y]_p(f) = X_p(Y(f)) - Y_p(X(f))$$

for every $f \in C^\infty(M)$ and $p \in M$.

Call $[X, Y]$ the Lie bracket of X and Y .

Exercise: prove lemma. To check: (a) $[X, Y]_p \in \text{Der}(C^\infty(p), \mathbb{R})$.

(the above defines it as in $\text{Hom}_{\mathbb{R}}(C^\infty(p), \mathbb{R})$)

(b) the map $[X, Y]: M \rightarrow TM$

$$p \mapsto (p, [X, Y]_p) \text{ is}$$

smooth, i.e., $[X, Y] \in \mathfrak{X}(M)$.

Prop: The Lie bracket satisfies the following properties:

(1) $[X, Y]$ is linear in both X & Y .

$$(2) [Y, X] = -[X, Y]$$

$$(3) [X, fY] = \underbrace{X(f)}_{\substack{\uparrow \\ \text{any } f \in C^\infty(M)}} \underbrace{Y}_{\substack{\uparrow \\ C^\infty(M)}} + f[X, Y]$$

(from (2)+(3) can also deduce $[fX, Y] = \dots$)

(4) (Jacobi identity):

$$[X, (Y, Z)] + [Y, (Z, X)] + [Z, (X, Y)] = 0.$$

$\forall X, Y, Z \in \mathfrak{X}(M)$.

(Remark: if had a different association $X, Y \rightsquigarrow \alpha(X, Y)$ vector field
 $\forall \alpha(fX, Y) = \alpha(X, fY) = f\alpha(X, Y)$, we say

α is torsional (not true for $[-, \cdot]$) $\leadsto \alpha$ comes from a section of the "torsion bundle"
 $T^*M \otimes T^*M$.

Distributions:

Idea: a nowhere vanishing vector field X determines a "smoothly varying" collection of 1-d subspaces $\text{span}(X_p) \subseteq T_p M$.

Integral curves of X give in particular maps $\gamma: I \rightarrow M$ w/
 $d\gamma(T_t I) \subseteq$ (or $=$ if immersion) $\text{span}(X_{\gamma(t)}) \subseteq T_{\gamma(t)} M$.

Distributions give a higher dimensional subspace generalization of the above.

Def: M^m . Fix $1 \leq c \leq m$. A c -dimensional distribution \mathcal{D} on M^m is a choice of c -dimensional subspace $\mathcal{D}_p \subseteq T_p M$ for each $p \in M$.

• Say \mathcal{D} is smooth if, at every $p \in M$, \exists nhood $U \ni p$ and c (smooth) vector fields X_1, \dots, X_c on U which span \mathcal{D} over U .

(i.e., $\text{span}(X_1|_q, \dots, X_c|_q) = \mathcal{D}_q$ for every $q \in U$).

i.e., $\mathcal{D} = \{\mathcal{D}_p\}_{p \in M}$

• Say a vector field X is contained in \mathcal{D} , written $X \in \mathcal{D}$ if $X_p \in \mathcal{D}_p$ for every p .

Def: Fix \mathcal{D} a smooth c -dim'l distribution on M^m . An integral submanifold $N^n \subseteq M^m$ of \mathcal{D} is a submanifold where $T_p N \subseteq \mathcal{D}_p \subseteq T_p M$ for every $p \in N$.

($\Rightarrow \dim N = n \leq \dim \mathcal{D} = c$).

Def: \mathcal{D} is integrable if at every p , \exists a chart (U, ϕ) and $\overset{p}{n}$ local coordinates x_1, \dots, x_m ($x_i := x_i \circ \phi$) such that

$\mathcal{D} = \text{Span} \left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_c} \right)$

(means $\mathcal{D}_q = \text{Span} \left(\frac{\partial}{\partial x_1}|_q, \dots, \frac{\partial}{\partial x_c}|_q \right)$ for every q in U)

\Leftrightarrow near any $p \exists$ functions f_1, \dots, f_{m-c} smooth functions on a neighborhood U of p such that for any constants k_1, \dots, k_{m-c} , the loci

$\{f_i = k_i, \dots, f_{m-c} = k_{m-c}\}$ are integral submanifolds of \mathcal{D} with $(f_1, \dots, f_{m-c}): U \rightarrow \mathbb{R}^{m-c}$ is a submersion.

We can specify distributions by:

(i.e., at every point)

• specifying c globally independent $X_1, \dots, X_c \in \mathcal{X}(M)$

$$\approx \mathcal{D} = \text{span}(X_1, \dots, X_c)$$

• dually, by specifying a globally independent $\theta_1, \dots, \theta_{m-c} \in \Omega^1(M)$

$$\approx \mathcal{D} = \bigcap_{i=1}^{m-c} \ker(\theta_i)$$

(note: each $(\theta_i)_p: T_p M \rightarrow \mathbb{R}$)

Ex: \mathbb{R}^3 , $\omega = dz \in \Omega^1(\mathbb{R}^3)$.

Then $\mathcal{D} = \ker \omega = \text{span} \left\{ \frac{\partial}{\partial x}, \frac{\partial}{\partial y} \right\}$.

The integral surfaces of \mathcal{D} are of the form $z = \{\text{const}\}$.

\mathcal{D} is an integrable 2-plane field distribution.

Ex: \mathbb{R}^3 , $\omega = dz + (x dy - y dx)$. Then

$$\mathcal{D} = \ker(\omega) \stackrel{\text{check}}{=} \text{span} \left\{ x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y}, y \frac{\partial}{\partial x} - x \frac{\partial}{\partial y} + \frac{\partial}{\partial z} \right\}$$

is not integrable. (first example of what's called a contact distribution.)

(exercise).

Q: When is \mathcal{D} integrable?

Case $\dim(\mathcal{D}) = 1$. By ODE theory we know that if $X_p \neq 0$ then $\text{Span}(X)$ is (at least locally near p) integrable. (Last class we showed if $X_p \neq 0$ then $X = \frac{\partial}{\partial x_1}$ in some coords near p)

\Rightarrow any 1-di'l \mathcal{D} is integrable.

Def: Say $\mathcal{D} \subset TM$ (smooth-di'l dist.) is involutive if, whenever

$X, Y \in \mathcal{D}$ then $[X, Y] \in \mathcal{D}$.

(" \mathcal{D} is closed under $[-, -]$ ").

Thm: [Frobenius theorem]: \mathcal{D} is integrable if and only if \mathcal{D} is involutive.

Start of proof sketch:

\Rightarrow Say \mathcal{D} is integrable. Then at each $p \exists$ ^{local} coordinates near p

$$\text{s.t. } \mathcal{D} = \text{Span} \left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_c} \right).$$

\Rightarrow Given $X, Y \in \mathcal{D}$ we can write $X = \sum_{i=1}^c a_i(x) \frac{\partial}{\partial x_i}$ & $Y = \sum_{j=1}^c b_j(x) \frac{\partial}{\partial x_j}$ near p in these coordinates, and we can compute

exercise: ^{near p} $[X, Y] = \sum_{j=1}^c \sum_{i=1}^c \left(a_i \frac{\partial b_j}{\partial x_i} \frac{\partial}{\partial x_j} - b_j \frac{\partial a_i}{\partial x_j} \frac{\partial}{\partial x_i} \right) \in \mathcal{D}$

$\Rightarrow [X, Y] \in \mathcal{D}$ for any $X, Y \in \mathcal{D}$. \square .

\Leftarrow next time (sketch).

\square .