

Today: focus primarily on  $E = TM$ ,  $E = T^*M$ .

From last time, we can form  $TM^{\otimes s}$ ,  $(T^*M)^{\otimes s}$ ,  $\Lambda^s T^*M$ ,  $\Lambda^s TM$ .

Let's focus on  $\Lambda^k T^*M$ , (dim  $M = m$ , so  $\Lambda^0 T^*M = \mathbb{R}$   $\leftarrow$  trivial bundle,  
 $\Lambda^1 T^*M = T^*M$

study their sections.

$\vdots$   
 $\Lambda^k T^*M$  has rank  $\binom{m}{k}$   
 $\vdots$   
 $\Lambda^m T^*M$  is a line bundle.  
 $\Lambda^i T^*M = \{0\}$  for  $i > m$ .

Sections of  $\Lambda^k T^*M$  are called (differential) k-forms (or differential forms of degree  $k$ ).

(Sections of  $\Lambda^k TM$  are called polyvectorfields).

When  $M = \mathbb{R}^m$ , we've previously seen that any 1-form is of the form  $\alpha = \sum f_i dx_i$

Similarly, any  $k$ -form must be of the form

$$\omega = \sum_{i_1 < \dots < i_k} g_{i_1 \dots i_k} dx_{i_1} \wedge \dots \wedge dx_{i_k} \quad (*) \quad (\text{exercise: verify})$$

$dx_i : p \mapsto (p, (dx_i)_p)$ .  
 where  $(dx_i)_p$  denotes  
 $[x_i - x_i(p)] \in \mathcal{F}_p / \mathcal{F}_p^2$ ,  
 $\mathcal{F}_p \subseteq C^\infty(p)$ .  
 $(dx_i)_p \in \mathcal{F}_p / \mathcal{F}_p^2 = T_p^* \mathbb{R}^m$ .

$\uparrow$   
 a smooth function.  
 $\uparrow$   
 the  $k$ -form whose value at  $p \in \mathbb{R}^m$  is  
 $(dx_{i_1})_p \wedge \dots \wedge (dx_{i_k})_p$ .  
 $\uparrow$   
 $T_p^* \mathbb{R}^m$ .  
 $\uparrow$   
 $\Lambda^k T_p^* \mathbb{R}^m = (\Lambda^k T^* \mathbb{R}^m)_p$ .

It follows that for any manifold  $M$ , any differential  $k$ -form  $\tau \in \Gamma(M; \Lambda^k T^*M)$  must have the form  $(*)$  in local coordinates with respect to some chart.

Notation:

$\Omega^k(M) := \Gamma(\Lambda^k T^*M)$ , the space of (differential)  $k$ -forms.

- a vector space over  $\mathbb{R}$ .
- moreover, a  $C^\infty(M)$ -module.

note this generalizes  $\Omega^0(M) = \Gamma(\Lambda^0 T^*M = \underline{\mathbb{R}}) = C^\infty(M)$

$$\Omega^1(M) = \Gamma(\Lambda^1 T^*M = T^*M).$$

Pull back: Let  $f: M \rightarrow N$  be a smooth map.

Then, there is a pull-back operation:

$$f^*: \Omega^k(N) \rightarrow \Omega^k(M),$$

$$\omega \longmapsto f^*\omega: p \longmapsto \left( p, \underbrace{(f_p^*)^{\wedge k}(\omega_{f(p)})}_{\substack{\uparrow \\ \Lambda^k T_p^* N}} \right)$$

check (exercise): This sends  $\Omega^k(N)$  to  $\Omega^k(M)$ ,

i.e., the result is a  $C^\infty$  section of  $\Lambda^k T^*M$ .

i.e., the result is smooth.

In local coordinates: say have

$$\tilde{f}: \mathbb{R}^m \rightarrow \mathbb{R}^n \text{ smooth map}$$

(e.g., by pre/post-composing by charts from  $f$  above).

$$\tilde{f} = (\tilde{f}_1, \dots, \tilde{f}_n),$$

if  $\omega \in \Omega^k(\mathbb{R}^n)$  was of the form  $\omega = \sum_{i_1 < \dots < i_k} g_{i_1 \dots i_k} dx_{i_1} \wedge \dots \wedge dx_{i_k}$ ,

$$\text{then } f^*\omega = \sum (g_{i_1 \dots i_k} \circ f) \underbrace{d\tilde{f}_{i_1}}_{\substack{\uparrow \\ d(x_{i_1} \circ \tilde{f}) \\ = d(\tilde{f}^* x_{i_1})}} \wedge \dots \wedge \underbrace{d\tilde{f}_{i_k}}_{\substack{\uparrow \\ d(x_{i_k} \circ \tilde{f} = \tilde{f}^* x_{i_k})}}.$$

$f^* g_{i_1 \dots i_k}$        $d(x_{i_1} \circ \tilde{f}) = d(\tilde{f}^* x_{i_1})$        $d(x_{i_k} \circ \tilde{f} = \tilde{f}^* x_{i_k})$ .

Diagram illustrating the pull-back operation:

- Top:  $\Lambda^k T_p^* M$  (purple)
- Middle:  $(f_p^*)^{\wedge k}(\omega_{f(p)})$  (purple)
- Bottom:  $\Lambda^k T_{f(p)}^* N$  (blue)
- Arrows:  $\downarrow$  from top to middle,  $\uparrow$  from bottom to middle,  $\rightarrow$  from middle to the right.

Recall:  $(f_p)_* = df_p: T_p M \rightarrow T_{f(p)} N$   
 $\Rightarrow (f_p)^*: T_{f(p)}^* N \rightarrow T_p^* M$   
 $\Rightarrow (f_p^*)^{\wedge k}: \Lambda^k T_{f(p)}^* N \rightarrow \Lambda^k T_p^* M$

## Exterior derivative

$$\text{Recall we defined } d: \underbrace{\Omega^0(M)}_{C^\infty(M)} \rightarrow \underbrace{\Omega^1(M)}_{\Gamma(T^*M)}$$
$$\underbrace{\quad}_{\Gamma(\wedge^1 T^*M)}$$

We can define an extension:

$$d_{(k)}: \Omega^k(M) \rightarrow \Omega^{k+1}(M)$$

$$\text{of } d = d_0: \Omega^0(M) \rightarrow \Omega^1(M),$$

defined as follows:

On Euclidean space:  $M = \mathbb{R}^m$  (or an open subset thereof)

(1) For  $f \in \Omega^0(\mathbb{R}^m)$ , recall  $df$  could be computed as:

$$df = \sum \frac{\partial f}{\partial x_i} dx_i$$

(2) If  $\omega = \sum f_I dx_I \in \Omega^k(\mathbb{R}^m)$ , where  $dx_I = dx_{i_1} \wedge \dots \wedge dx_{i_k}$   
if  $I = (i_1, \dots, i_k)$ ,

$$\text{define } d_k \omega = \sum_I df_I \wedge dx_I \in \Omega^{k+1}(\mathbb{R}^m).$$

(example): (i)  $\omega = xyz dx + y dy$  on  $\mathbb{R}^3$ .

$$d\omega = d(xyz) \wedge dx + d(y) \wedge dy.$$

$$= \left( \frac{\partial}{\partial x}(xyz) dx \wedge dx + \frac{\partial}{\partial y}(xyz) dy \wedge dx + \frac{\partial}{\partial z}(xyz) dz \wedge dx \right) + dy \wedge dy$$

$$= -xz dx \wedge dy - xy dx \wedge dz.$$

(ii)  $\omega = f dx \wedge dy \wedge dz$  on  $\mathbb{R}^3$ .

$$d\omega = df \wedge dx \wedge dy \wedge dz (= 0 \text{ b/c } \wedge^4 T^*\mathbb{R}^3 = \{0\}, \text{ or } \dots)$$

$$= (f_x dx + f_y dy + f_z dz) \wedge dx \wedge dy \wedge dz = 0 + 0 + 0 = 0.$$

To define  $d$  on a more general  $M$ :

Given  $\omega \in \Omega^k(M)$ , let's define  $d\omega \in \Omega^{k+1}(M)$ . <sup>Pick  $p \in M$ .</sup> suffices to define  $d\omega$  in some neighborhood of  $p$  (as  $p$  was arbitrary), provided we check well-definedness.

Choose a chart  $(U, \phi)$  around  $p$  giving a diffeo.

$$\begin{array}{ccc}
 U & \xrightleftharpoons[\phi^{-1}]{\phi} & \phi(U) \subseteq \mathbb{R}^m \\
 & & \text{open} \\
 \Omega^k(\phi(U)) & \xrightarrow{d_k \text{ (defined above)}} & \Omega^{k+1}(\phi(U)) \\
 \uparrow (\phi^{-1})^* & & \downarrow \phi^* \\
 \Omega^k(U) & \xrightarrow{\text{--- } d_k \text{ defined ---}} & \Omega^{k+1}(U) \\
 \downarrow \omega|_U & & \text{Define } (d_k \omega)|_U := \phi^* d_k((\phi^{-1})^* \omega|_U)
 \end{array}$$

to make diagram commut.

Prop: this is independent of chart chosen. (exercise), & gives a well-defined

$$d_k: \Omega^k(M) \rightarrow \Omega^{k+1}(M).$$

frequently call  $d$ , suppress  $k$ .

Example on  $\mathbb{R}^3$ :  
( $x, y, z$ ):

$$0 \rightarrow \Omega^0 \xrightarrow{d} \Omega^1 \xrightarrow{d} \Omega^2 \xrightarrow{d} \Omega^3 \rightarrow 0$$

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz \quad (\approx \text{'gradient'})$$

$$d(fdx + gdy + hdz) = \left( \frac{\partial h}{\partial x} - \frac{\partial f}{\partial z} \right) dx \wedge dz \quad (\approx \text{'curl'})$$

$$+ \left( \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dx \wedge dy$$

$$+ \left( \frac{\partial h}{\partial y} - \frac{\partial g}{\partial z} \right) dy \wedge dz.$$

$$d(f_1 dy \wedge dz + f_2 dz \wedge dx + f_3 dx \wedge dy)$$

$$= \left( \frac{\partial f_1}{\partial x} + \frac{\partial f_2}{\partial y} + \frac{\partial f_3}{\partial z} \right) dx \wedge dy \wedge dz. \quad (\approx \text{'divergence'})$$

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OH: (Zoom) M 12:45-1:45pm, W 2-3, Th 4:30-5:30.

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