

## Last time: Homotopy invariance

Def: Two maps  $\phi_0, \phi_1 : M \rightarrow N$  are smoothly homotopic if there exists a smooth map  $\Phi : M \times [0,1] \rightarrow N$  with  $\Phi(-,0) = \phi_0(-)$ ,  $\Phi(-,1) = \phi_1(-)$ .

Using the notation  $\phi_t := \Phi(-,t)$ ,

"there exists a smoothly varying family  $\{\phi_t\}$  interpolating between  $\phi_0$  &  $\phi_1$ ".

write  $\phi_0 \sim \phi_1$  if they are homotopic.

which we have it yet proven!

Prop: (Homotopy invariance): Say  $\phi_t$  is <sup>smooth</sup> homotopy,  $t \in [0,1]$ . Then  $(\phi_t : M \rightarrow N)$

$\phi_t^* : H^k(N) \rightarrow H^k(M)$  is independent of t.

(i.e.,  $\Rightarrow$  If  $\phi_0 \sim \phi_1$ , then  $\phi_1^* = \phi_0^* : H^k(N) \rightarrow H^k(M)$ ).

Def: A <sup>(smooth)</sup> map  $\phi : M \rightarrow N$  is a homotopy equivalence if  $\exists$  a homotopy inverse

up to homotopy, i.e., a  $\psi : N \rightarrow M$  (smooth) with

$$\psi \circ \phi \simeq \text{id}_M$$

call  $\psi$  "homotopy inverse"

$$\phi \circ \psi \simeq \text{id}_N.$$

Cor: If  $\phi : M \rightarrow N$  is a homotopy equivalence, then  $\phi^* : H^k(N) \rightarrow H^k(M)$  is an isomorphism.

Proof: Let  $\psi : N \rightarrow M$  be a homotopy inverse of  $\phi$ . Then

$$\phi^* \circ \psi^* = (\psi \circ \phi)^* = (\text{id}_N)^* = \text{id}_{H^k(M)}.$$

$$\psi^* \circ \phi^* = (\phi \circ \psi)^* = (\text{id}_M)^* = \text{id}_{H^k(N)}. \quad \square$$

N.B. Diffeomorphisms are homotopy equivalences, but not nec. vice versa. E.g., there can be homotopy equivalences between manifolds of different dimensions, such as:

Cor: (Poincaré Lemma):  $H_{dR}^k(\mathbb{R}^n) = 0$  if  $k > 0$ . (already know  $H_{dR}^0(\mathbb{R}^n) = \mathbb{R}$ ),

meaning: for  $k > 0$ , every closed  $k$ -form is also exact.

Proof: We'll show  $\mathbb{R}^n$  is homotopy equivalent to  $\mathbb{R}^0 = \{\text{pt}\} = \{0\}$ .

By above this will imply  $H_{dR}^k(\mathbb{R}^n) \cong H_{dR}^k(\{\text{pt}\}) = \begin{cases} 0 & \text{when } k > 0 \\ \mathbb{R} & \text{when } k = 0 \end{cases}$ .

$$\begin{array}{ll} \text{Let } \phi: \mathbb{R}^n \rightarrow \mathbb{R}^0 & \psi: \mathbb{R}^0 \rightarrow \mathbb{R}^n \\ (x_1, \dots, x_n) \mapsto 0. & 0 \longmapsto (0, \dots, 0) = \vec{0}. \end{array}$$

Claim:  $\phi, \psi$  are homotopy inverses.

- note  $\phi \circ \psi: \mathbb{R}^0 \rightarrow \mathbb{R}^0 = \text{id}_{\mathbb{R}^0}$ . ✓.  
 $0 \mapsto \vec{0} \mapsto 0.$

- $\psi \circ \phi: \mathbb{R}^n \rightarrow \mathbb{R}^n = f_0$  is homotopic to  $f_1 = \text{id}_{\mathbb{R}^n}$   
 $(x_1, \dots, x_n) \mapsto 0 \mapsto \vec{0}.$

via

$$f_t: \mathbb{R}^n \rightarrow \mathbb{R}^n \quad \begin{cases} t=0: \text{get } f_0 = \psi \circ \phi \\ t=1: \text{get } f_1 = \text{id}_{\mathbb{R}^n} \end{cases}$$

$$(x_1, \dots, x_n) \mapsto (tx_1, \dots, tx_n).$$

(note that the map  $F: \mathbb{R}^n \times [0, 1] \rightarrow \mathbb{R}^n$  is smooth).  
 $(x_1, \dots, x_n), t \mapsto (tx_1, \dots, tx_n)$   
 $f_t(\vec{x})$

□.

So assuming homotopy invariance, we get  $H_{dR}^k(\mathbb{R}^n)$

for e.g.,  $H_{dR}^k(\text{an open ball in } \mathbb{R}^n) \cong H^k(\mathbb{R}^n)$  ( $b/c \underset{\text{in } \mathbb{R}^n}{\text{open ball}} \underset{\text{diff}}{\cong} \mathbb{R}^n$ ).

Want to develop more tools for computing  $H_{dR}^k(M)$ .

Idea: decompose  $M = \bigcup U_i$  each  $U_i$  open. (and e.g.,  $U_i \underset{\text{diff}}{\cong}$  open ball in  $\mathbb{R}^n \underset{\text{diff}}{\cong} \mathbb{R}^n$ ),

we understand  $H^k(M)$ ? Can we reconstruct  $H^k(M)$ ?

Yes!

### Mayer-Vietoris Sequence

Let  $M = U \cup V$ ,  $U, V$  open sets. Then, we have natural inclusion maps

$$U \xrightarrow{i} M = U \cup V$$

$$V \xrightarrow{i} M = U \cup V.$$

$$U \cap V \xrightarrow{i_u} U$$

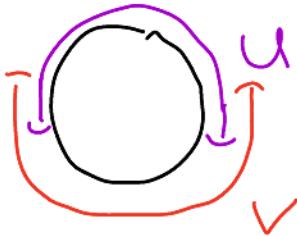
$$U \cap V \xrightarrow{i_v} V.$$

which we can alternatively think of as:

$$(*) \quad U \cap V \xrightarrow{i_u, i_v} U \sqcup V \xrightarrow{i} U \cup V$$

Example:

$$S^1.$$



$$M = S^1 = U \cup V$$

$$U \cong \mathbb{R}$$

$$V \cong \mathbb{R}$$

$$U \cap V \cong \mathbb{R} \times \mathbb{R},$$

" $M - V$ "



Thm (Mayer-Vietoris sequence):

Given a decomposition of  $M = U \cup V$  as above in (\*), we obtain the following long-exact-sequence (LES) of cohomology groups:

$$0 \rightarrow H^0(M) \xrightarrow{i^*} H^0(U) \oplus H^0(V) \xrightarrow{i_u^* - i_v^*} H^0(U \cap V) \rightarrow H^1(U \cup V)$$

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 $H^i(U \sqcup V)$ 

$$\rightarrow H^i(M) \xrightarrow{i^*} H^i(U) \oplus H^i(V) \xrightarrow{i_u^* - i_v^*} H^i(U \cap V) \xrightarrow{\delta} \dots$$

Pf: later.

Recall that a sequence of vector spaces  $\dots \xrightarrow{f_{i-1}} V^i \xrightarrow{f_i} V^{i+1} \xrightarrow{} \dots$ is said to be exact if  $\ker f_i = \text{im } f_{i-1}$  for every  $i$ .(long exact sequence : an exact sequence w/  $\geq 3$  non-zero terms)

LES

Note: (a)  $0 \rightarrow A \xrightarrow{i} B$  exact means  $\ker i = \text{im}(0) = 0$ .  $\Leftrightarrow i$  injective

↑ necessarily 0

(b)  $A \xrightarrow{j} B \rightarrow 0$  exact means  $j$  is surjective(c)  $0 \rightarrow A \rightarrow 0$  exact means  $A \cong 0$ (d)  $0 \rightarrow A \xrightarrow{i} B \rightarrow 0$  exact means  $i$  is an isomorphism (a) + (b) apply(e)  $0 \rightarrow A \xrightarrow{i} B \xrightarrow{j} C \rightarrow 0$  exact means•  $i$  injective•  $j$  surjective.

(short exact sequence, or SES)

•  $\ker j = \text{im } i$ .since  $B/\ker j \xrightarrow{j} \text{im } j = C$  $\xrightarrow{\quad\quad\quad}$   
 $B/i(A)$ ↳ a subspace isomorphic to  $A$ .

Example:  $M = S^1$ , with  $U, V$  as above

$$U \cong \mathbb{R}$$

$$V \cong \mathbb{R}$$

$$U \cap V \cong \mathbb{R} \sqcup \mathbb{R}$$

Compute  $H_{\text{dR}}^k(M = S^1 = U \cup V)$  using M-V. sequence.

Have (from theorems) a LES:

$$0 \rightarrow H^0(S^1) \rightarrow H^0(\mathbb{R}) \oplus H^0(\mathbb{R}) \rightarrow H^0(U \cap V = \mathbb{R} \sqcup \mathbb{R}) \rightarrow 0$$

$\delta$

~~$H^1(S^1) \rightarrow H^1(\mathbb{R}) \oplus H^1(\mathbb{R}) \rightarrow H^1(\mathbb{R} \sqcup \mathbb{R}) \rightarrow H^2(S^1) \rightarrow H^2(\mathbb{R}) \oplus H^2(\mathbb{R}) \rightarrow 0$~~

$\Rightarrow H^1(S^1) = 0$  by above

$\Rightarrow H^k(S^1) = 0$  for  $k \geq 2$  by identical reasoning (using  $H^i(\mathbb{R}) = 0$  for  $i > 0$ ).

$\Rightarrow A = 0$ .

Rewriting our LES, have:

$$0 \rightarrow H^0(S^1) \xrightarrow{i^*} H^0(\mathbb{R}) \oplus H^0(\mathbb{R}) \xrightarrow{i_u^* - i_v^*} H^0(\mathbb{R} \sqcup \mathbb{R}) \xrightarrow{\delta} H^1(S^1) \rightarrow 0$$

$\mathbb{R}^2$   
 $\mathbb{R} \oplus \mathbb{R}$

$\mathbb{R}^2$   
 $\mathbb{R} \sqcup \mathbb{R}$

$i^*$  injective by exactness at  $H^0(S^1)$ .

$$\text{so } \dim \text{im}(i^*) = 1.$$

• exactness at  $H^0(\mathbb{R}) \oplus H^0(\mathbb{R})$

$$\Rightarrow \dim \ker(i_u^* - i_v^*) = \dim (\text{im } i^*) = 1 \text{ by above.}$$

•  $\ker(*)$  has dimension 1.

$$\text{therefore } \dim \text{im } (*) = \dim \left( \frac{\text{domain}(*)}{\ker(*)} \right) = 2 - 1 = 1.$$

rank nullity

- By exactness at  $H^0(\mathbb{R} \amalg \mathbb{R})$ ,

$$\dim \ker \delta = \dim \text{im } (\ast) = 1.$$

- Rank nullity  $\Rightarrow \dim \text{im } \delta = \dim (\text{domain of } \delta) - \dim (\ker \delta)$   
 $= 2 - 1 = 1.$

- exactness  $\Rightarrow \text{im } \delta \cong H^1(S')$ , so  $\dim_{\mathbb{R}} H^1(S') = 1$ .

$$\Rightarrow H^1(S') \cong \mathbb{R}.$$