

Today: Integrations of differential forms

Goal: Define, for M^n an oriented manifold, and $\omega \in \Omega_c^m(M)$, an integral $\int_M \omega$.

cpct. support (vacuous if M cpct.)

depends on orientation of M up to sign.

In \mathbb{R}^m , have Riemann integral, roughly defined as follows:

$$R = [a_1, b_1] \times \dots \times [a_n, b_n] \subset \mathbb{R}^m \quad \text{'rectangle'}$$

Consider $f: R \rightarrow \mathbb{R}$

OR $f: U \rightarrow \mathbb{R}$ $U \subset \mathbb{R}^m$ f has cpct. support.

$$\text{In the first case, define } \int_R f dx_1 \dots dx_n = \lim_{P \text{ partitions of } R} U(f, P) = \lim_{P \text{ partitions of } R} L(f, P)$$

'upper Riemann sum if f assoc. to partition'

P partitions of R

P partitions of R

'lower Riemann sum'

f 'integrable' \Rightarrow these limits exist and are equal, & therefore \int_R well-defined.

rectangles in R

Given a partition $P = (P_1, \dots, P_k)$,

$$U(f, P) = \sum \text{vol}(P_i) \cdot \sup(f|_{P_i})$$

$$L(f, P) = \sum \text{vol}(P_i) \cdot \inf(f|_{P_i})$$

If f is continuous \Rightarrow it's integrable (in particular, smooth f 's are integrable)

In second case $f: U \rightarrow \mathbb{R}$ w/ cpct. support, choose $R \supset \text{supp } f$, &

extend f to $\bar{f}: R \rightarrow \mathbb{R}$ (extension necessary if $R \not\subset U$)

by 0, i.e., $\bar{f}(r) = 0$ if $r \notin \text{supp } f$.

$$\& \text{ define } \int_U f dx_1 \dots dx_n := \int_R \bar{f} dx_1 \dots dx_n \quad (\text{check independent of choice of } R)$$

change of variables formula:

In 1D:

If $g: [a, b] \rightarrow [c, d]$ smooth diffeo, then

$$\int_{g(a)}^{g(b)} f dx = \int_a^b (f \circ g) g' dx.$$

$\int_c^d f dx$ if g orientation preserving (so $g' > 0$)
 $-\int_c^d f dx$ if g orientation reversing (so $g' < 0$)

can rewrite as follows:

$$\int_{g(a,b)} f dx = \int_a^b f \circ g |g'| dx.$$

meas \int_c^d

$$\begin{aligned}
 U &\subseteq \mathbb{R}^m \text{ open } \mathbb{R}^{x_1 \rightarrow x_m} \\
 \phi &\downarrow \cong \\
 V &\subseteq \mathbb{R}^n \text{ open } \mathbb{R}^{y_1 \rightarrow y_n}
 \end{aligned}$$

More generally, if U, V open sets in \mathbb{R}^m w/ coordinates (x_1, \dots, x_m) , (y_1, \dots, y_n) & $\phi: U \xrightarrow{\cong} V$ diffeomorphism, & $f: V \rightarrow \mathbb{R}$ w/ compact support, then

$$\int_V f(y) dy_1 \dots dy_n = \int_U f(\phi(x)) |d\phi| dx_1 \dots dx_m$$

$$\phi = (\phi_1, \dots, \phi_n)$$

shorthand for $|\det(d\phi)|$.

abs. value of determinant of the total deriv/Jacobian matrix

$$d\phi = \left[\frac{\partial \phi_i}{\partial x_j} \right]_{i,j}$$

Integration of forms

Consider first $V \subseteq \mathbb{R}^n$ open $\mathbb{R}^{y_1 \rightarrow y_n}$ & $\omega \in \Omega_c^m(V)$, so $\omega = f dy_1 \wedge \dots \wedge dy_n$.

Proposal is to define $\int_V \omega := \int_V f dy_1 \dots dy_n$.

Diffeomorphism invariant? Say $\phi: U \xrightarrow{\cong} V$, then

$$\int_U \phi^* \omega \stackrel{??}{=} \int_V \omega$$

$$\begin{aligned}
 \text{Note } \int_U \phi^* \omega &= \int_U (f \circ \phi) d\phi_1 \wedge \dots \wedge d\phi_n \\
 &= \int_U (f \circ \phi) \det(d\phi) dx_1 \wedge \dots \wedge dx_m
 \end{aligned}$$

$$\begin{aligned}
 \phi &= (\phi_1, \dots, \phi_n) \\
 d\phi_i &= \sum \frac{\partial \phi_i}{\partial x_j} dx_j
 \end{aligned}$$

$$:= \int_U (f \circ \phi) \det(d\phi) dx_1 \dots dx_n$$

$$\stackrel{\text{change of variables formula}}{=} \int_V f dy_1 \dots dy_m = \int_V \omega$$

equality only holds if $\det(d\phi) = |\det(d\phi)|$, i.e., if $\det(d\phi) > 0$ everywhere.

i.e., $\int_V \omega = \int_U \phi^* \omega$ if $\phi: U \xrightarrow{\cong} V$ was orientation preserving.

(if it does, say M orientable)

Recall: An orientation on M^m (if exists), e.g., a choice of component of $\Lambda^m TM \setminus \{0\}$ or a component of $\Lambda^m T^*M \setminus \{0\}$ or an equiv. class of nowhere vanishing top form up to pos. scaling,

induces a (maximal) oriented atlas $\mathcal{A}_{or, max} \subset \mathcal{A}_{(M, \pi)}$ consisting of those

(U, ϕ) s.t. $\phi: U \xrightarrow{\cong} \phi(U)$ is orientation preserving (for std orientation on \mathbb{R}^m & one on U induced by chosen orientation on M)

For any pair of such $(U, \phi), (V, \psi)$, the transition fns.

$\psi \circ \phi^{-1}: \phi(U \cap V) \xrightarrow{\cong} \psi(U \cap V)$ is an oriented diffeo. (so $\det(d(\psi \circ \phi^{-1})) > 0$)

Thm: Given an oriented M^m , \exists a unique linear map

$$\int_M (-) : \Omega_c^m(M) \longrightarrow \mathbb{R}.$$

such that for any $\omega \in \Omega_c^m(M)$ with $\text{supp}(\omega) \subset U_\alpha$, w/ $(U_\alpha, \phi_\alpha) \in \mathcal{A}_{or, max}$,

$$\mathcal{B} (\phi_\alpha^{-1})^* \omega = f_\alpha dx_1 \wedge \dots \wedge dx_m \in \Omega_c^m(\phi_\alpha(U_\alpha)),$$

$$\text{then } \int_M \omega = \int_{\phi_\alpha(U_\alpha)} (\phi_\alpha^{-1})^* \omega = \int_{\phi_\alpha(U_\alpha)} f_\alpha dx_1 \wedge \dots \wedge dx_m. \quad (\star)$$

Proof start/sketch: Let $\omega \in \Omega_c^m(M)$

(i) • If $\text{supp } \omega \subseteq U_\alpha$, where $(U_\alpha, \phi_\alpha) \in \mathcal{A}_{or, \max}$. Then,
we use $\phi_\alpha: U_\alpha \xrightarrow{\cong} \phi_\alpha(U_\alpha)$ to define $\int_M \omega$ as in (*).

(ii) • More generally, pick an oriented atlas $\mathcal{A}_{or} \subseteq \mathcal{A}_{or, \max}$ which is locally finite &
 $\mathcal{A}_{or} = \{(U_\alpha, \phi_\alpha)\}_{\alpha \in I}$, & let $\{\psi_\alpha\}_{\alpha \in I}$ be a partition of unity
subordinate to U_α .

Then $\omega = \sum_\alpha \psi_\alpha \omega$; but now each $\psi_\alpha \omega$ is supported in U_α ,

hence $\int_M \psi_\alpha \omega$ is already defined above, now linearity forces us to define

$$\int_M \omega = \sum_\alpha \int_M \psi_\alpha \omega = \sum_\alpha \int_{\phi_\alpha(U_\alpha)} (\phi_\alpha^{-1})^* (\psi_\alpha \omega).$$

↑
well-defined (finite sum over α by compact support of ω ; restrict to finitely many U_α covering $\text{supp}(\omega)$).

Exercise: check that this ^{proposed} definition is well-defined i.e., doesn't depend on
choice of oriented atlas made or choice of $\{\psi_\alpha\}$ subordinate to U_α .

(e.g., in (i), say $\text{supp } \omega \subset (U_\alpha, \phi_\alpha)$ and $\text{supp } \omega \subset (U_\beta, \phi_\beta)$.

$$\text{Then } \int_M \omega = \int_{\phi_\alpha(U_\alpha)} (\phi_\alpha^{-1})^* \omega = \int_{\phi_\alpha(U_\alpha)} (\phi_\alpha^{-1})^* \phi_\beta^* (\phi_\beta^{-1})^* \omega$$

$$\text{vs. } \int_M \omega = \int_{\phi_\beta(U_\beta)} (\phi_\beta^{-1})^* \omega \quad \underbrace{= \int_{\phi_\alpha(U_\alpha)} (\phi_\beta \circ \phi_\alpha^{-1})^* (\phi_\beta^{-1})^* \omega}_{\text{b/c } \det(\phi_\beta \circ \phi_\alpha^{-1}) > 0}$$

by oriented condition
 $\phi_\beta \circ \phi_\alpha^{-1}$ oriented diffeo. by hypothesis