

K. Fukaya, Maslov's index in divisor classes (work in progress w/ A. Daems) 11/18/2016

$(X, \omega)$  symplectic manifold,  $J$ .  $D \subset X$  codim. 2 sm.  $\eta$ -field.

Assume:  $J$  is integrable in a neighborhood of  $D$ , &  $D \subset X$  complex submanifold.

Consider  $L \subset X \setminus D$  Lagrangian submanifold.

Def:  $L \subset X \setminus D$  is monotone  $\iff \exists c > 0$  s.t.  $\forall (D^2, \partial D^2) \xrightarrow{u} (X \setminus D, L)$ ,  
 then  $\int u^* \omega = c \eta(u)$ , Maslov index.

(key point: only putting this assumption for disks outside  $D$ )

Thm: If  $L_1, L_2 \subset X \setminus D$  are monotone &  $\eta(u) > 2$ ,  
all discs on either  $L_i$ ?

$\Rightarrow \exists$  HF( $L_1, L_2; X \setminus D$ ) satisfying:  
 $\mathbb{R}$ -vec. space

(1) Inv. of Ham. diffeos on  $X \setminus D$

(2) If  $L_1 \pitchfork L_2$ ,  $\#(L_1 \cap L_2) \geq \text{rk HF}$ .

(3)  $\exists$  spectral seq.  $H^*(L) \Rightarrow \text{HF}(L, L; X \setminus D)$ .

(Remarks: don't know that it only depends on  $X \setminus D$ ; may depend on  $D$ )

Notes:

(1) If  $D = \emptyset$ , then  $[0, h]$

(2) If  $X \setminus D$  is convex, then basically also

main thing here is no assumptions about convexity of  $X \setminus D$ .

Possible generalizations

(a)  $D$  can be a normal crossings divisor.

(b)  $G \curvearrowright X$  and  $D, L_i$  are  $G$ -invariant; then can do things equivalently;  
 $\text{HF}_G(L_1, L_2; X \setminus D)$ .

(c)  $\eta: X \rightarrow \mathcal{G}^*$  moment map,  $L_1, L_2 \subset \eta^{-1}(0)$   $G$ -invariant  $\left\{ \begin{array}{l} \text{just need banding cocycles} \\ \text{(no need for bulk classes)} \end{array} \right.$   
 Then, expect to show  $\text{HF}_G(L_1, L_2; X \setminus D) \cong \text{HF}^*((L_1/G, b_1), (L_2/G, b_2))$   $\left\{ \begin{array}{l} \text{el } G \text{ free on } \eta^{-1}(0) \\ Y = X/G \end{array} \right.$

① <sup>cool ups</sup> Filtered Assoc category  $\mathcal{A}, \mathcal{O}(X \setminus D)$   
 in general, curved objects  $(L, b)$   $L \subset X \setminus D$ , where, if  $L$  is nowhere  $c \times D \Rightarrow L$  is unobstructed,  $b$  can take  $b=0$ .

②  $R = \Delta_0 \ll t_a's, t_b's \gg$ .

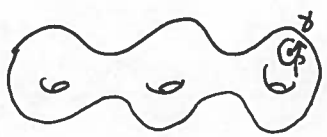
where:  $a=1, \dots, m$   $m = \text{rk } H_*(D)$   
 $b=1, \dots, m'$   $m' = \text{rk } H_*(X \setminus D)$ .

Can extend  $\text{Fuk}(X \setminus D)$  to one over  $R$ , with  $t=0$  gives ①.

One application:

[Manolescu-Woodward]:

Take  $\Sigma_g$ , Riem. surface genus  $g$ , &  $G$  a cpct. semisimple Lie group.

Consider  the pair  $\{(\nabla, \mathcal{F}) \mid \nabla \text{ flat connection on } \Sigma/p, \omega / \text{hol}_\gamma = \exp \mathcal{F}\} / \mathcal{G}_0$   
 $\parallel$   
 $\check{R}(\Sigma_g; G)$   
 (Rmk:  $\mathcal{G}$  seems related to geom. Langlands, but  $G$  cpct. grp, not opt.  $\rightarrow$  mod. real part?)  
 $\uparrow$   
 gauge transf:  $g$   
 $\omega(g(p)) = \text{id}$ .

[Hebichman-Jeffrey]:  $\check{R}(\Sigma, G)$  has a 2-form  $\omega$  w/  $d\omega = 0$ , where  $\omega$  is degenerate only on a small part.

$\gamma : \check{R}(\Sigma_g, G) \rightarrow \mathcal{O}_\gamma$  is a moment map for a  $G$  action,  $\omega /$

$\check{R}(\Sigma, G) // G = R(\Sigma, G)$  : moduli of flat  $G$ -bundles.

[Manolescu-Woodward: propose using  $\check{R}$  to understand Lajn flux theory in  $\omega$  potentials to, e.g., Atiyah-Floer]

If  $\partial H_g = \Sigma_g$   $H_g$  is a handle body, this induces

$$\widehat{R}(H_g; G) = \text{Hom}(\pi_1 H_g, G) \hookrightarrow \eta^{-1}(0) \subset R(\Sigma; G)$$

$\eta^{-1}(0)$  is a Lie group manifold,  $G$ -equiv.   
 $R(\Sigma; G)$  is  $G$ -equiv.

Also, [M.W] are a non-abelian symplectic cut:

$$\check{X} = \check{R}(\Sigma, G) \xrightarrow{\eta} \text{or} \xrightarrow{\text{Ad action}} \mathbb{C}G \xrightarrow{\text{Weyl chamber}} W$$

Take a polygon  $\subset W$  nbhd. of 0 (certain good polygons), call it  $\Delta$ .

The <sup>non-ab.</sup> sympl. cut is:  $\eta^{-1}(\overset{\circ}{\Delta}) \cup \eta^{-1}(\partial \Delta^{\text{ex}}) / \sim \quad \} =: X(\Delta)$

[Woodward-Meincken]:

Ex:  $S^1 \times G = SU(2)$

$$X \longrightarrow W = [0, \infty) \quad \text{Consider } \varepsilon > 0, \text{ \& take}$$

$$\eta^{-1}((0, \varepsilon)) \cup \eta^{-1}(\varepsilon) / S^1$$

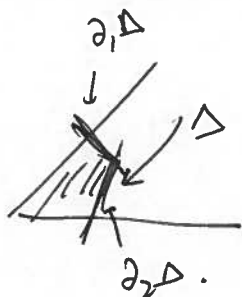
Have:  $X(\Delta) = \eta^{-1}(\overset{\circ}{\Delta}) \cup \eta^{-1}(\partial \Delta) / \sim$

$$\overset{\cup}{\mathcal{D}} = \eta^{-1}(\partial \Delta)$$

↑ normal crossings divisor Smooth of  $G = SU(2)$

Ex:  $G = SU(3)$

$W =$



Then,  $X(\Delta) = \eta^{-1}(\overset{\circ}{\Delta}) \cup \eta^{-1}(\partial_1 \overset{\text{ex}}{\Delta}) / S^1$

$$\cup \eta^{-1}(\partial_2 \overset{\text{ex}}{\Delta}) / S^1 \cup \eta^{-1}(\partial_1 \Delta \cap \partial_2 \Delta) / \eta$$

Prove:  $X(\Delta)$  smooth sympl. manifold (no degenerate locus for  $\Delta$  small

&  $\mathcal{D}$  smooth n.c. divisor).

↑ (smpl. form non-deg near 0)

Back to  $\check{X} = \check{R}(\Sigma, G) \xrightarrow{\bar{\eta}} \mathcal{Y} \longrightarrow W \cong \Delta$ .

If have  $\Delta \subset W$  & get  $X(\Delta)$ .

Then, for a handle body  $H_g$  in fact

$\check{R}(H_g, G) \xrightarrow{\text{Logn.}} \bar{\eta}^{-1}(0) \subset X(\Delta)$   
 is monotone in  $X(\Delta) \setminus \mathcal{D}$ .

Conj: If  $M^3 = H_g^1 \cup_{\Sigma_g} H_g^2$ , then

$\text{HF}_G^x(\check{R}(H_g^1, G), \check{R}(H_g^2, G); X(\Delta) \setminus \mathcal{D})$

is an invariant of the 3 manifold  $M$ .

(If  $G = \text{SU}(2)$ , should give symp. side of Atiyah-Floer).

[MW]: Case  $G = \text{SU}(2)$ . Then, ~~have~~ considered:

$$X = R(\Sigma, \text{SU}(2)) \xrightarrow{\bar{\eta}} [0, \infty)$$

&  $X(\frac{1}{2}) = \bar{\eta}^{-1}([0, \frac{1}{2})) \cup \bar{\eta}^{-1}(\frac{1}{2}) / S^1$  is a degenerate  
 symp. manifold, but is monotone (without even removing  $\mathcal{D}$ ). <sup>[MW]</sup> ~~they~~ managed here

to define  $\text{HF}(\check{R}(H_g^1, \text{SU}(2)), \check{R}(H_g^2, \text{SU}(2)), X \setminus \mathcal{D})$

↳ suggest  $\exists$  an  $\text{SU}(2)$ -equivariant version.

↑ is equivalent, using monotonicity  $\mathcal{D}$  is  $X$ .

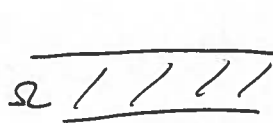
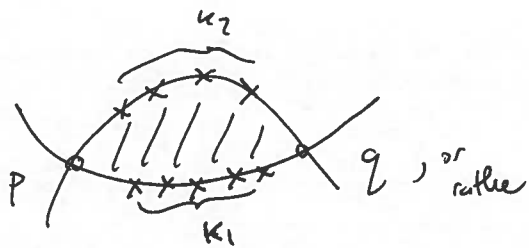
Can also imagine generalization to toric  $\mathcal{O}^3$ s. (non-compact, non-convex;

use fixed pt. localizations to define GW invariants (is not a priori defined)

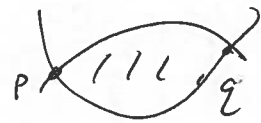
Can use this same cut trick to get compact symp. manifold, w/  $\mathcal{D}$ , &  $X \setminus \mathcal{D}$  is  $(Y$

Sketch of proof:

Say have  $L_1, L_2 \subset X \setminus D$ ,  $\beta$  consider



J-hol.  $\xrightarrow{u}$



w/  $u(\Omega) \subset X \setminus D$

Gives  $\mathcal{M}_{k_1, k_2}(p, q; X \setminus D, \beta)$ ,  $\beta = [u]$   
 ← noncompactified.

Issue: how to compactify? If  $X \setminus D$  convex, maximum principle + usual compactification.

~~Types of breaking~~: Another moduli spaces:

$$u: (D^2, \partial D^2) \rightarrow (X \setminus D, L) \rightsquigarrow \mathcal{M}_{k+1}^0(L, X \setminus D; \beta)$$



$$[u] = \beta$$

holo.

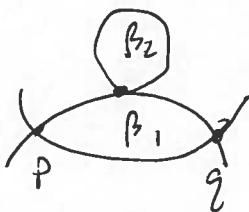
Main Lemma: Can compactify

$$\mathcal{M}_{k_1, k_2}(p, q; X \setminus D, \beta) \text{ \& } \mathcal{M}_{k+1}^0(L; X \setminus D, \beta)$$

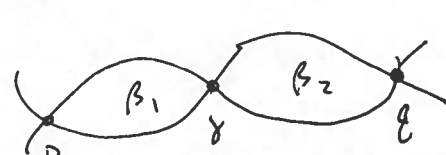
w/  $\partial \mathcal{M}_{0,0}(p, q, X \setminus D, \beta)$  has components:

(a)  $\mathcal{M}_{0,0}(p, q, X \setminus D, \beta_1) \times \mathcal{M}_{0,0}(r, q, X \setminus D, \beta_2)$

(b)  $\mathcal{M}_{1,0}(p, q, X \setminus D, \beta_1) \times \mathcal{M}_{1,1}(L_1, \beta_2)$



$$u([\beta_i] \cdot [D]) = 0$$



$$u([\beta_i] \cdot D) = 0$$

key point: usual compactification doesn't catch this

Note: as usual, Max Lemma  $\xrightarrow{\text{st. number less than } k+1}$  Main theorem

Prob: The usual stable maps compactification does not satisfy this!

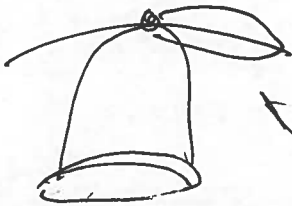
Need relative GW theory type compactification:

(J. Li, A. M. Li - Ruan, Javel-Parker, B. Parker, Teleman - Zinger)

Stable map compactification:

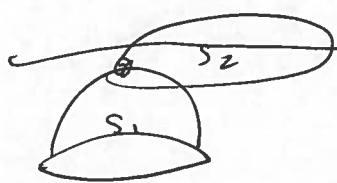


← If map is smooth, won't touch D, but



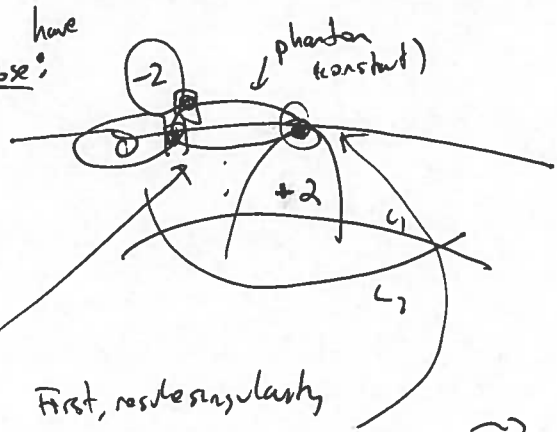
configurations may happen. If  $D \cdot D > 0$ , the this is also positive, so total  $n$  w/  $D$  is positive, why tho out:

But can have:



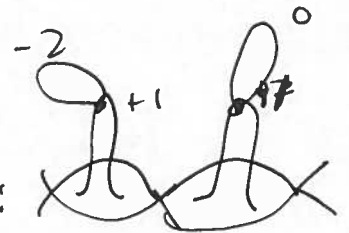
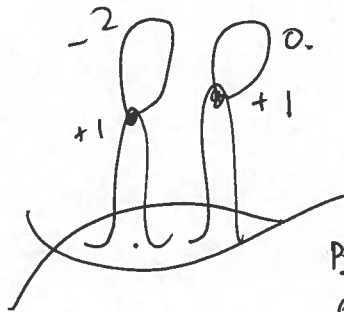
$S^2 \cdot D < 0$   
 $S_1 \cdot D > 0$  , so total  $\cdot D = 0$

Suppose:



$D$ . Then, in total have intersection 0.

gues

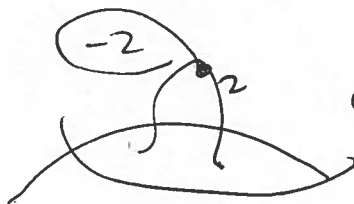


problematic: can split

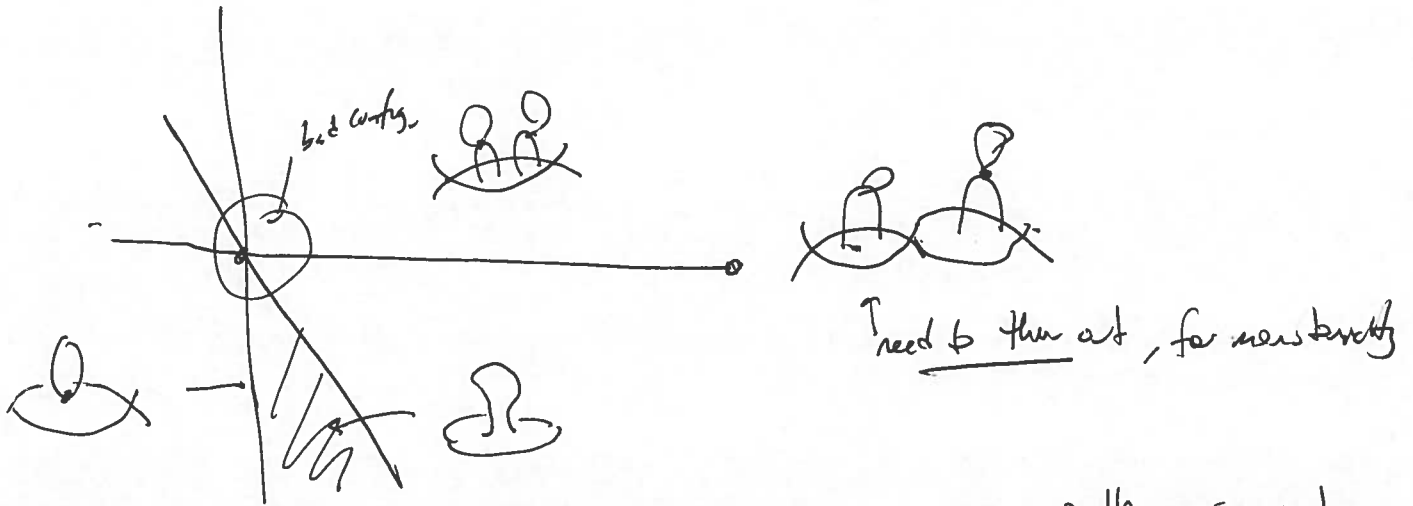
contract

can never be a handling class in  $X \setminus D$ !

But, if resolve  $D$ ; then get



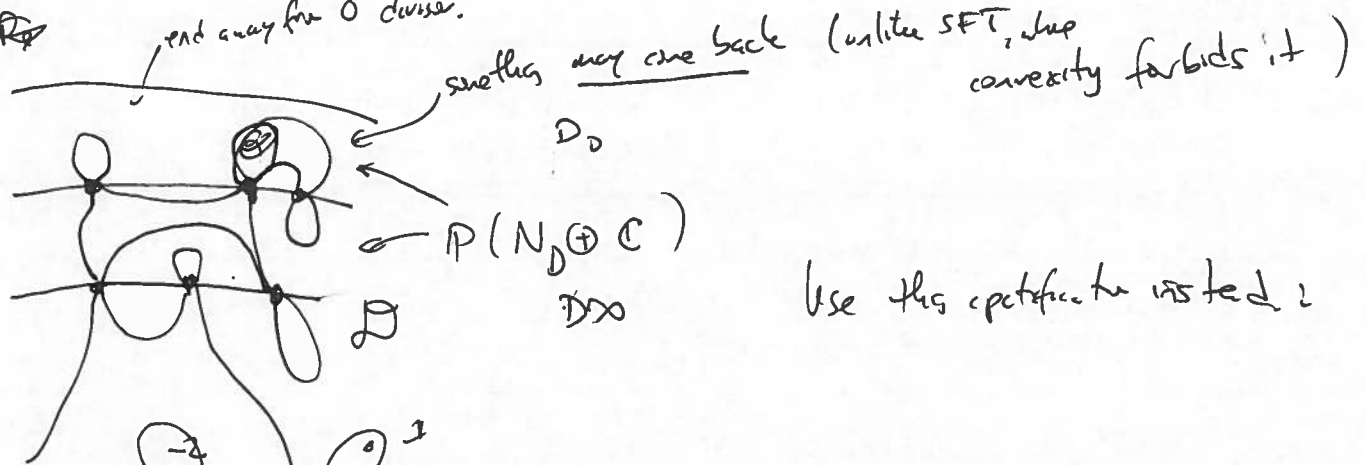
ok!! So, funny things: need to keep this & throw out



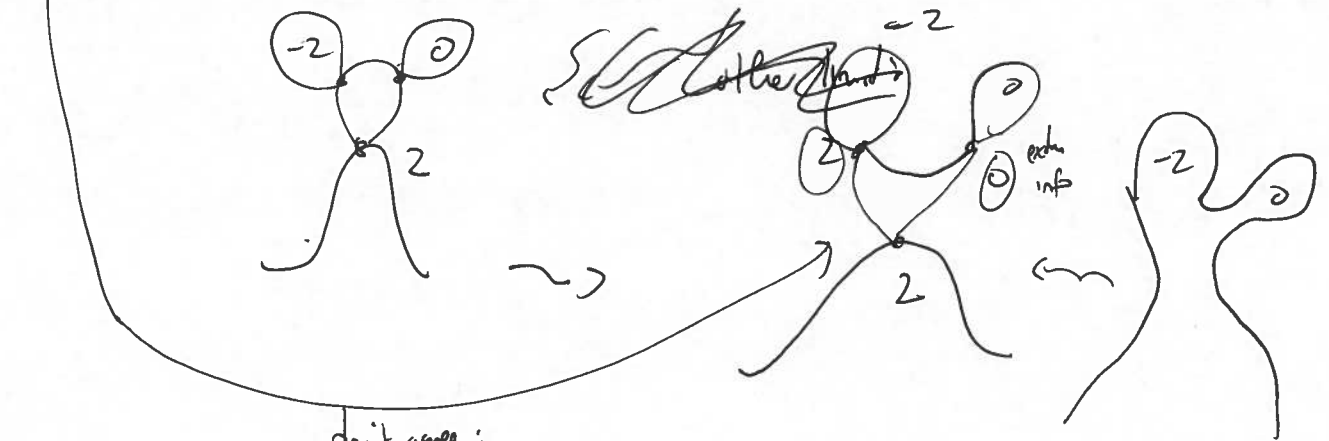
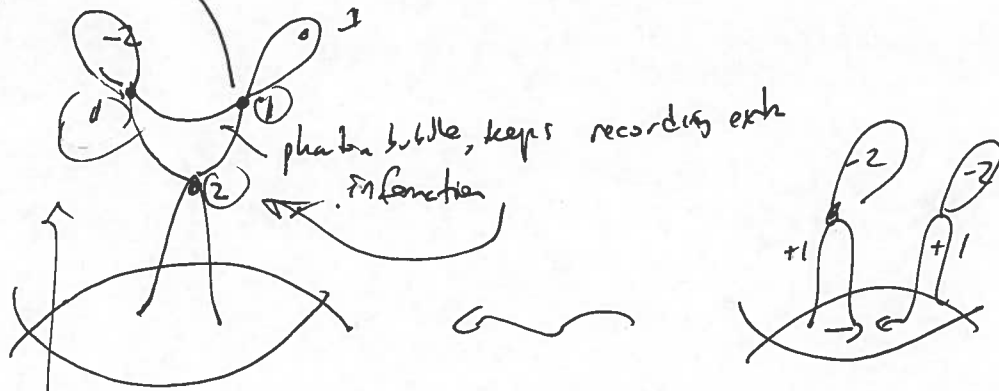
need settling here: away from dance

problem was usual  
stable map optimization

end away from 0 dance.



use this certificate instead:



so, can safely thin out LHS, which is good. Can also understand settling close to SFT here.