

Math 113 Midterm Exam—Solutions

Held Thursday, May 7, 2013, 7 - 9 pm.

1. (10 points) Let V be a vector space over \mathbb{F} and $T : V \rightarrow V$ be a linear operator. Suppose that there is a non-zero vector $\mathbf{v} \in V$ such that $T^3\mathbf{v} = T\mathbf{v}$. Show that at least one of the numbers 0, 1, -1 is an eigenvalue of T .

Solution: We have that $T^3\mathbf{v} = T\mathbf{v}$ for some nonzero vector \mathbf{v} . Therefore $(T^3 - T)\mathbf{v} = 0$. Powers of the linear map T commute with one another, so we may rewrite this as $T(T - I)(T + I)\mathbf{v} = 0$. Now, there are several cases:

Case 1: $\mathbf{v} \in \ker(T + I)$:

Then \mathbf{v} is a nonzero -1 -eigenvector of T .

Case 2: $\mathbf{v} \notin \ker(T + I)$, so $(T + I)\mathbf{v} \neq 0$, but $(T + I)\mathbf{v} \in \ker(T - I)$:

Then $(T + I)\mathbf{v}$ is a nonzero 1 -eigenvector of T .

Case 3: $(T + I)\mathbf{v} \notin \ker(T - I)$:

Then $(T - I)(T + I)\mathbf{v}$ is not the zero vector. But $T(T - I)(T + I)\mathbf{v} = 0$, so $(T - I)(T + I)\mathbf{v}$ is a nonzero 0 -eigenvector of T .

Therefore we have a nonzero eigenvector of T with eigenvalue -1 , 1 or 0 , so at least one of these must be an eigenvalue of T .

Alternatively, it was acceptable to directly note that because $T(T - I)(T + I)\mathbf{v} = 0$, one of T , $T - I$ or $T + I$ must not be injective (because in order to have this equality with \mathbf{v} non-zero, at some point, one of the operators T , $T - I$, or $T + I$ must send a non-zero vector to zero).

Common mistakes:

- Somehow using $T^3\mathbf{v} = T\mathbf{v}$ for all \mathbf{v} , rather than just for one fixed \mathbf{v} .
- Thinking that $T\mathbf{v} = 0$ for some \mathbf{v} meant that T was the zero operator.
- Similarly, thinking that $T\mathbf{v} = \mathbf{v}$ for some \mathbf{v} meant that T was the identity operator.

- Proving the converse – that if T has an eigenvalue of 1, -1 or 0 , then there is a nonzero vector \mathbf{v} with $T^3\mathbf{v} = T\mathbf{v}$.
 - Getting $T(T - I)(T + I)\mathbf{v} = 0$, and then claiming that \mathbf{v} was in either $\ker(T)$, $\ker(T + I)$ or $\ker(T - I)$.
2. (35 points total, 7 points each) *Prove or disprove.* For each of the following statements, say whether the statement is True or False. Then, prove the statement if it is true, or disprove (find a counterexample with justification) if it is false. (Note: simply stating “True” or “False” will receive no credit).
- (a) If the only eigenvalue of a linear map $T : V \rightarrow V$ is 0 , then T is the zero map.

Solution: *False.* Consider the map $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ sending $(x, y) \mapsto (y, 0)$. As we discussed in class, there is only one eigenvalue, 0 , but clearly T is not the zero map.

More generally, if T is any linear map whose matrix for some basis is upper triangular, with all 0 's on the diagonal, then in class (and in Axler) we showed that the only eigenvalue of T is 0 . However, this matrix corresponding to T could have arbitrary entries above the diagonal, and thus need not be the zero matrix.

- (b) Let V be a vector space of dimension n , and $\mathcal{P}_{n-1}(\mathbb{F})$ denote polynomials with degree less than or equal to $n - 1$. Then, $\mathcal{L}(V, \mathbb{F})$ is isomorphic to $\mathcal{P}_{n-1}(\mathbb{F})$.

Solution: *True.* Note that $V^* = \mathcal{L}(V, \mathbb{F})$ has the same dimension of V , which is n (either by a homework problem or the textbook), and $\mathcal{P}_{n-1}(\mathbb{F})$, which has standard basis $(1, x, \dots, x^{n-1})$ also has dimension n . And any two finite-dimensional vector spaces with the same dimension are isomorphic, by results from class.

- (c) Let U and V be 4-dimensional subspaces of \mathbb{R}^7 . Then U and V contain a common non-zero vector.

Solution: *True.* By the dimension formula from class/Axler,

$$\dim(U + V) = \dim U + \dim V - \dim(U \cap V) = 4 + 4 - \dim(U \cap V)$$

but $U + V$ is a subspace of \mathbb{R}^7 , so $\dim(U + V) \leq 7$. We conclude that $\dim(U \cap V) \geq 1$, so in particular $U \cap V$ contains a non-zero vector.

(d) Let $T : V \rightarrow V$ be a linear transformation. Then, V is the direct sum of its subspaces $\ker T$ and $\operatorname{im} T$. That is, $V = \ker T \oplus \operatorname{im} T$.

Solution: *False.* Consider the same map as part (a), $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$, $(x, y) \mapsto (y, 0)$. Note that $\ker T = \{(x, 0)\}$ and $\operatorname{im}(T) = \{(x, 0)\}$. In particular, $\ker T + \operatorname{im}(T) = \{(x, 0)\}$, which is not equal to all of \mathbb{R}^2 .

(e) Let V be finite-dimensional and let $S, T : V \rightarrow V$ satisfy $ST = \mathbf{0}_V$. Then $\dim \operatorname{im}(S) + \dim \operatorname{im}(T) \leq \dim(V)$.

Solution: *True.* First note that $ST = \mathbf{0}_V$ implies that $\operatorname{im}(T) \subset \ker S$, so

$$\dim \operatorname{im}(T) \leq \dim \ker(S). \tag{1}$$

Now, by the rank-nullity theorem

$$\dim \ker(S) + \dim \operatorname{im}(S) = \dim V,$$

which together with (1) implies the desired statement.

3. (25 points total) *Annihilators and quotients.* Let V be a vector space over \mathbb{F} . Recall that we defined the *dual space* V^* to be the vector space of linear maps from V to \mathbb{F} ,

$$V^* = \mathcal{L}(V, \mathbb{F}).$$

Now, let $S \subset V$ be a subset. Define the *annihilator of S* to be the following subspace of V^* :

$$\operatorname{Ann}(S) := \{T : V \rightarrow \mathbb{F} \mid T(s) = \mathbf{0} \text{ for all } s \in S\}.$$

In words, $\operatorname{Ann}(S)$ is the subset of linear functionals that *annihilate all of S* , i.e. those functionals that send every element of S to $\mathbf{0}$.

(a) (10 points) Prove that $\text{Ann}(S)$ is a subspace of V^* , and that

$$\text{Ann}(S) = \text{Ann}(\text{span}(S)).$$

Solution: By definition, $\text{Ann}(S)$ is a subset of V^* . We simply need to prove it's a subspace by verifying the following assertions:

- $\mathbf{0} \in \text{Ann}(S)$. This is because $\mathbf{0}(s) = 0$ for every $s \in S$ (indeed $\mathbf{0}$ applied to any vector is 0).
- Additive closure: Say $f, g \in \text{Ann}(S)$. Then, for any $s \in S$, note that $(f + g)(s) = f(s) + g(s) = 0 + 0 = 0$, so $f + g \in \text{Ann}(S)$.
- Closure under scalar multiplication: Say $f \in \text{Ann}(S)$. Then, for any scalar c , note that $(cf)(s) = c \cdot f(s) = c \cdot 0 = 0$, so $cf \in \text{Ann}(S)$.

Now, let's show $\text{Ann}(S) = \text{Ann}(\text{span}(S))$. Note clearly that $\text{Ann}(\text{span}(S)) \subset \text{Ann}(S)$, because any functional that annihilates all of $\text{span}(S)$ certainly annihilates S , which is a subset of $\text{span}(S)$. So we need to show the other inclusion: $\text{Ann}(S) \subset \text{Ann}(\text{span}(S))$. Let $f \in \text{Ann}(S)$. Then, consider any element \mathbf{v} of $\text{span}(S)$, which can be written as a linear combination

$$a_0s_0 + \cdots + a_k s_k$$

of elements of S . We check that, since f is linear,

$$f(a_0s_0 + \cdots + a_k s_k) = a_0f(s_0) + \cdots + a_k f(s_k) = 0,$$

as $f(s_i) = 0$ for all $s_i \in S$. Thus, $f(\mathbf{v}) = 0$ for any $\mathbf{v} \in \text{span}(S)$, so $f \in \text{Ann}(\text{span}(S))$.

(b) (10 points) Now, let U and W be two subspaces of a V . Prove that $\text{Ann}(U + W) = \text{Ann}(U) \cap \text{Ann}(W)$.

Solution: We'll show both inclusions: First let $f \in \text{Ann}(U + W)$. Then f annihilates any vector of the form $\mathbf{u} + \mathbf{w}$ for $\mathbf{u} \in U$, $\mathbf{w} \in W$. In particular, f annihilates any $\mathbf{u} \in U$ and any $\mathbf{w} \in W$ (which can be represented as $\mathbf{u} + 0$ and $0 + \mathbf{w}$ respectively), so $f \in \text{Ann}(U) \cap \text{Ann}(W)$.

Next, suppose $f \in \text{Ann}(U) \cap \text{Ann}(W)$. Then f annihilates any vector in U and any vector in W . Thus, note that if $\mathbf{u} \in U$ and $\mathbf{w} \in W$, by linearity,

$$f(\mathbf{u} + \mathbf{w}) = f(\mathbf{u}) + f(\mathbf{w}) = 0$$

which means f annihilates any element in $U + W$, i.e. $f \in \text{Ann}(U + W)$.

- (c) (5 points) If W is a subspace of V , let V/W denote the quotient of V by W and let $(V/W)^*$ denote its linear dual. Construct a *canonical* (not using a basis) linear map

$$f_W : \text{Ann}(W) \longrightarrow (V/W)^*.$$

other than the zero map (in fact, this map should be invertible). Also, define the inverse f_W^{-1} of this map (though you do not need to carefully check that $f_W \circ f_W^{-1} = I$ and $f_W^{-1} \circ f_W = I$.)

Solution: Let $T \in \text{Ann}(W)$, so T is a linear map $T : V \rightarrow \mathbb{F}$ that sends $W \rightarrow 0$. By the homework and class, that means T induces a well-defined map on the quotient $\bar{T} : V/W \rightarrow \mathbb{F}$, so $\bar{T} \in (V/W)^*$. Define $f_W(T) = \bar{T}$.

Let $\pi_W : V \rightarrow V/W$ denote the natural projection map we defined in homework. Then to a linear transformation $S : V/W \rightarrow \mathbb{F}$, define

$$f_W^{-1}(S) := S \circ \pi_W : V \rightarrow \mathbb{F}.$$

Note that since $\ker \pi_W = W$, $S \circ \pi_W$ annihilates W , so indeed, $S \circ \pi_W \in \text{Ann}(W)$.

Common mistakes:

- (a)
- Neglecting to check that $\text{Ann}(\text{Span}(S)) \subseteq \text{Ann}(S)$
 - Assuming that S was finite.
 - Attempting to consider an infinite sum of vectors, which is undefined.
- (b)
- Showing only one of the inclusions and claiming that the other was obvious.

- Attempting to give a vague verbal description of the subspaces involved
 - “This space is the set of all operators which do this and that to U and V , and so is the other side, so they’re equal”.
- (c) • Defining a function which didn’t have the correct domain and/or codomain.

4. (20 points total, 10 points each) *Linear maps, kernels, and images.*

- (a) Let $T : V \rightarrow W$ and $S : W \rightarrow U$ be linear maps between finite-dimensional vector spaces. Prove that if T is surjective, then

$$\dim(\ker ST) = \dim(\ker S) + \dim(\ker T).$$

Solution: We will apply the rank-nullity theorem to each of the maps S, T and ST . We have that T is surjective, so $\text{im}(T) = W$ and $\text{im}(ST) = \text{im}(S)$:

$$\begin{aligned} \dim(\ker(S)) + \dim(\ker(T)) &= \dim(W) - \dim(\text{im}(S)) + \dim(V) - \dim(\text{im}(T)) \\ &= \dim(W) - \dim(\text{im}(S)) + \dim(V) - \dim(W) \\ &= \dim(V) - \dim(\text{im}(S)) \\ &= \dim(V) - \dim(\text{im}(ST)) \\ &= \dim(\ker(ST)). \end{aligned}$$

Therefore $\dim(\ker(S)) + \dim(\ker(T)) = \dim(\ker(ST))$, as required.

- (b) Now, suppose $S, T \in \mathcal{L}(V)$, and V is finite-dimensional. Prove that $\ker S \subseteq \ker T$ if and only if there exists a linear map $R \in \mathcal{L}(V)$ with $T = RS$.

Solution: If there exists a linear map R with $T = RS$, then let v be any element of $\ker(S)$. Then $T(v) = R(S(v)) = R(0) = 0$, so $v \in \ker(T)$. Therefore $\ker(S) \subseteq \ker(T)$.

Now, assume that $\ker(S) \subseteq \ker(T)$. We would like to define a linear map R such that $T(v) = R(S(v))$ for each $v \in V$. Firstly, define R on the image of S by $R(S(v)) = T(v)$. We need to check that this definition is well-defined. That is, if $S(v_1) = S(v_2)$ then $R(S(v_1)) = R(S(v_2))$.

If $S(v_1) = S(v_2)$, then $S(v_1 - v_2) = 0$, so $(v_1 - v_2) \in \ker(S)$, so $(v_1 - v_2) \in \ker(T)$, which means that $T(v_1 - v_2) = 0$ and so $T(v_1) = T(v_2)$. Hence by the

definition of R , $R(S(v_1)) = R(S(v_2))$. Therefore our map R is well-defined on its domain, $\text{im}(S)$, and satisfies $R(S(v)) = T(v)$ for any $v \in V$.

Finally, extend a basis of $\text{im}(S)$ to a basis of V and define R arbitrarily on that basis. This produces a map $R \in \mathcal{L}(V)$ with $T = RS$.

5. (15 points) Let V denote the subspace of continuous functions from \mathbb{R} to \mathbb{R} spanned by the functions $\cos x$, $\sin x$, $x \cos x$, and $x \sin x$. Let $T : V \rightarrow V$ be the linear map defined by

$$(Tf)(x) := f(x + \pi) + f(-x).$$

Find an eigenbasis of V with respect to the linear map T . What is the matrix of T with respect to this basis? (Don't forget: $\sin(x + \pi) = -\sin x$, and $\cos(x + \pi) = -\cos x$).

Solution: First, we apply T to each element of the given basis:

$$T(\cos(x)) = 0$$

$$T(\sin(x)) = -2 \sin(x)$$

$$T(x \cos(x)) = -2x \cos(x) - \pi \cos(x)$$

$$T(x \sin(x)) = -\pi \sin(x)$$

This shows that $\cos(x)$ and $\sin(x)$ are eigenvectors of T with eigenvalues 0 and -2 . To find two more eigenvectors, we try linear combinations of $\cos(x)$ and $x \cos(x)$ and of $\sin(x)$ and $x \sin(x)$. (To motivate this, look at what T does to each of these vectors).

We find that $(x \cos(x) - \frac{\pi}{2} \cos(x))$ and $(x \sin(x) - \frac{\pi}{2} \sin(x))$ are eigenvectors of T with eigenvalues -2 and 0. It is easily checked that the four eigenvalues we have given are linearly independent, thus are a basis of V . (Adding a multiple of one vector to another does not change the subspace that they span).

The matrix of T with respect to the eigenbasis

$$\left\{ \cos(x), \sin(x), x \cos(x) - \frac{\pi}{2} \cos(x), x \sin(x) - \frac{\pi}{2} \sin(x) \right\}$$

is

$$M = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & -2 & 0 & 0 \\ 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

Common mistakes:

- Finding that $\cos(x)$ and $\sin(x)$ are eigenvectors and the other two are not, and concluding that there are only two eigenvectors.
6. (15 points) *An invariant subspace.* Let V be a vector space with dimension n . Suppose $T : V \rightarrow V$ is a linear transformation with n *distinct* eigenvalues $\lambda_1, \dots, \lambda_n$ and corresponding eigenvectors $\mathbf{v}_1, \dots, \mathbf{v}_n$. Set

$$\mathbf{v} = \mathbf{v}_1 + \dots + \mathbf{v}_n$$

and consider the subspace W spanned by the vectors $\{\mathbf{v}, T\mathbf{v}, T^2\mathbf{v}, T^3\mathbf{v}, \dots\}$ (W is the smallest T -invariant subspace containing \mathbf{v}). Prove that $W = V$.

Solution: Note that W is a span of elements which are all in V , so $W \subset V$. Thus, in order to show that $W = V$, it suffices to show that $\dim(W) = n$, which we will do by showing that the collection $\{v, Tv, T^2v, \dots, T^{n-1}v\}$ is linearly independent. Consider any linear dependence relation

$$a_0v + a_1Tv + \dots + a_{n-1}T^{n-1}v = 0. \tag{2}$$

Because each v_j is an eigenvector of T with eigenvalue λ_j , we have that

$$\begin{aligned} T^i(v) &= T^i(v_1 + v_2 + \dots + v_n) \\ &= \lambda_1^i v_1 + \lambda_2^i v_2 + \dots + \lambda_n^i v_n. \end{aligned}$$

Substituting this into Equation 2, we get that

$$p(\lambda_1)v_1 + p(\lambda_2)v_2 + \dots + p(\lambda_n)v_n = 0,$$

where $p(x)$ is the polynomial $a_0 + a_1x + \dots + a_{n-1}x^{n-1}$. But eigenvectors corresponding to different eigenvalues are linearly independent, so

$$p(\lambda_1) = p(\lambda_2) = \dots = p(\lambda_n) = 0.$$

Therefore the polynomial p has n distinct roots, $\lambda_1, \dots, \lambda_n$. But p has degree at most $n - 1$, so p must be the zero polynomial. Hence, each a_i is zero.

We have shown that if $a_0v + a_1Tv + \dots + a_{n-1}T^{n-1}v = 0$ then each a_i is zero, so the set $\{v, Tv, T^2v, \dots, T^{n-1}v\}$ is linearly independent. Therefore $\dim(W) = n$, so $W = V$, as required.

7. (20 points total) *Matrices and polynomials.*

- (a) (5 points) Let V and W be finite-dimensional vector spaces over \mathbb{F} , and $T : V \rightarrow W$ be a linear map. Give a definition of the matrix of T with respect to a pair of bases (one for V and one for W). **Solution:** Given a basis $\underline{v} = (\mathbf{v}_1, \dots, \mathbf{v}_n)$ of V and $\underline{w} = (\mathbf{w}_1, \dots, \mathbf{w}_m)$ of W , the matrix of T with respect to $\underline{v}, \underline{w}$, denoted

$$\mathcal{M}(T, \underline{v}, \underline{w})$$

is a particular $m \times n$ array of scalars, indexed as

$$\begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \quad (3)$$

where a_{ij} is the scalar such that, when $T\mathbf{v}_j$ is expressed as a linear combination of \underline{w} , a_{ij} is the coefficient of \mathbf{w}_i . Namely, the scalars a_{ij} are the unique scalars that satisfy

$$T\mathbf{v}_j = a_{1j}\mathbf{w}_1 + \dots + a_{ij}\mathbf{w}_i + \dots + a_{mj}\mathbf{w}_m.$$

- (b) (15 points) Let $V = \mathcal{P}_2(\mathbb{R})$ denote the vector space of polynomials of degree ≤ 2 with real coefficients. Consider the standard basis

$$\underline{v} = (\mathbf{v}_1 = 1, \mathbf{v}_2 = x, \mathbf{v}_3 = x^2)$$

of $\mathcal{P}_2(\mathbb{R})$. On homework, you showed that the dual vector space $V^* = \mathcal{L}(V, \mathbb{R})$ has an induced *dual basis*

$$\underline{\mathbf{v}}^* := (\mathbf{v}_1^*, \mathbf{v}_2^*, \mathbf{v}_3^*),$$

where \mathbf{v}_i^* is the linear map from V to \mathbb{R} defined by

$$\mathbf{v}_i^*(\mathbf{v}_j) = \begin{cases} 1 & j = i \\ 0 & j \neq i. \end{cases}$$

Now, let $T : V \rightarrow V^*$ be the linear map defined by

$$p \mapsto f_p$$

where $f_p \in V^* = (\mathcal{P}_2(\mathbb{R}))^*$ is the functional defined by

$$f_p(q) := \int_{-1}^1 p(x)q(x)dx$$

(You do not need to prove this is a linear map). Determine the matrix of T with respect to the bases $\underline{\mathbf{v}}$, $\underline{\mathbf{v}}^*$.

Solution: We need to apply the recipe from part (a). Namely, we need to express $T\mathbf{v}_1$, $T\mathbf{v}_2$ and $T\mathbf{v}_3$ as linear combinations of elements of $\underline{\mathbf{v}}^*$.

First, $T\mathbf{v}_1 = T(1) = f_1$. f_1 is the functional whose values on basis elements $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ are

$$\begin{aligned} f_1(1) &= \int_{-1}^1 1dx = x|_{-1}^1 = 2 \\ f_1(x) &= \int_{-1}^1 xdx = \frac{1}{2}x^2|_{-1}^1 = 0 \\ f_1(x^2) &= \int_{-1}^1 x^2dx = \frac{1}{3}x^3|_{-1}^1 = \frac{2}{3}. \end{aligned}$$

Since $2\mathbf{v}_1^* + \frac{2}{3}\mathbf{v}_3^*$ is a functional taking the same values on the basis elements $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$, we conclude that

$$T\mathbf{v}_1 = f_1 = 2\mathbf{v}_1^* + \frac{2}{3}\mathbf{v}_3^*.$$

Now, $T\mathbf{v}_2 = T(x) = f_x$, which is the functional whose values on the basis $\underline{\mathbf{v}}$ are

$$\begin{aligned} f_x(1) &= \int_{-1}^1 x dx = 0. \\ f_x(x) &= \int_{-1}^1 x^2 dx = \frac{2}{3} \\ f_x(x^2) &= \int_{-1}^1 x^3 dx = \frac{1}{4}x^4 \Big|_{-1}^1 = 0. \end{aligned}$$

(where some of these integrals agree with earlier calculations). Hence, in a similar fashion $T\mathbf{v}_2 = f_x = \frac{2}{3}\mathbf{v}_2^*$.

Finally, $T\mathbf{v}_3 = T(x^2) = f_{x^2}$, which is the functional whose values on the basis $\underline{\mathbf{v}}$ are

$$\begin{aligned} f_{x^2}(1) &= \int_{-1}^1 x^2 dx = \frac{2}{3} \\ f_{x^2}(x) &= \int_{-1}^1 x^3 dx = \frac{1}{4}x^4 \Big|_{-1}^1 = 0 \\ f_{x^2}(x^2) &= \int_{-1}^1 x^4 dx = \frac{1}{5}x^5 \Big|_{-1}^1 = \frac{2}{5}. \end{aligned}$$

i.e. $T\mathbf{v}_3 = f_{x^2} = \frac{2}{3}\mathbf{v}_1^* + \frac{2}{5}\mathbf{v}_3^*$.

Applying this to the definition of matrix, we finally get that

$$\mathcal{M}(T, \underline{\mathbf{v}}, \underline{\mathbf{v}}^*) = \begin{bmatrix} 2 & 0 & \frac{2}{3} \\ 0 & \frac{2}{3} & 0 \\ \frac{2}{3} & 0 & \frac{2}{5} \end{bmatrix}. \quad (4)$$

Common mistakes:

- Mixing up the rows and columns of the matrix, or the corresponding subscripts.
- Misunderstanding the dual space $(\mathcal{P}_2(\mathbb{R}))^*$. For example, only attempting to apply f_1 to 1, f_x to x and f_{x^2} to x^2 .